AMENDMENTS TO THE CLAIMS

The following listing of claims will replace all prior versions and listings of claims in the application.

LISTING OF CLAIMS

1. A method for controlling acceleration behavior of a vehicle comprising:

determining a pedal voltage;

filtering the pedal voltage at a predetermined filter rate (alpha), the predetermined filter rate being a function of an engine speed and a vehicle speed; determining the difference between the pedal voltage and the filtered pedal voltage;

[[determining a rate of change of a pedal position]] selecting a performance mode based on the difference, [[rate of change,]] wherein the performance mode is indicative of performance characteristics of an engine;

determining an acceleration condition; and controlling acceleration according to the performance mode and the acceleration condition.

- 2. (original) The method of claim 1 wherein determining the acceleration condition includes determining the acceleration condition according to at least one of turbine speed, engine speed, vehicle speed, engine acceleration, vehicle acceleration, and pedal movement.
- 3. (original) The method of claim 1 wherein the performance characteristics include transmission ratio and power request damping.
- 4. (original) The method of claim 1 wherein controlling the acceleration includes adjusting acceleration according to the performance mode if the acceleration condition is a first value.
- 5. (original) The method of claim 4 further comprising selecting a default performance mode if the acceleration condition is a second value.
- 6. (original) The method of claim 4 further comprising maintaining the performance mode for a first period if the acceleration condition is the first value.
 - 7-10. (cancelled)

11. (currently amended) An electronic throttle controller comprising:

a first module <u>receiving a pedal voltage signal and filtering said</u> pedal voltage signal at a predetermined filter rate (alpha) dependent upon an engine speed and a vehicle speed, and using said pedal voltage and filtered pedal voltage to determine [[that determines]] a rate of change of a pedal position;

a second module that selects a performance mode according to the rate of change;

a third module that generates an acceleration signal, wherein the acceleration signal is indicative of a duration of acceleration; and

a controller that communicates with the second module and the third module and controls acceleration according to the performance mode and the acceleration signal.

12-13. (cancelled)

- 14. (original) The electronic throttle controller according to claim 11 wherein the acceleration signal is a first value if a vehicle speed, an engine speed, and the pedal position are constant.
- 15. (original) The electronic throttle controller according to claim 14 wherein the acceleration signal is a second value if at least one of the vehicle speed, the engine speed, and the pedal position are not constant.

- 16. (original) The electronic throttle controller according to claim 15 wherein the controller adjusts the acceleration according to the performance mode if the acceleration signal is the second value.
- 17. (original) The electronic throttle controller according to claim 11 wherein controlling the acceleration includes at least one of adjusting a transmission ratio and damping a power request.
 - 18. (currently amended) An electronic throttle controller comprising: a sensor that determines a pedal voltage;

a filter that filters the pedal voltage to generate a filtered pedal voltage, said filter having a predetermined filter rate (alpha) dependent upon an engine speed and a vehicle speed;

a comparator that compares the pedal voltage to the filtered pedal voltage;

a controller that communicates with the comparator and selects a performance mode if a rate of change of the pedal voltage exceeds a rate of change of the filtered pedal voltage by a threshold.